Josheta Srinivasan

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DDUCATION

EDUCATION	
University of Southern California, Viterbi School of Engineering	GPA: 4.0
B.S. Computer Engineering and Computer Science	May 2024
Honors: Center for Undergraduate Research in Viterbi Engineering fellow	Fall 2021-Spring 2022
Involvement: Center for Al in Society (CAIS++), Society of Women Engineers, Theta Tau Kappa Epsilon	
<u>Relevant Coursework:</u> Data Structures and Algorithms, Probability, Internet of Things, Principles of Software Development,	
Linear Circuits, Digital Circuits, Linear Algebra and Differential Equations, Calculus 3	
Indiana University - Bloomington, Luddy School of Informatics, Computing and Engineering	GPA: 4.0
Intelligent Systems Engineering (track: Cyber-Physical System), Cognitive Science	Jan 2020-May 2021
TECHNICAL SKILLS	
Micro-controllers: Raspberry Pi, Arduino, FPGAs Technical Writing: Research reports, summaries and posters; Projection	ct documentation; Software
documentation; Academic papers Programming: Python, C, C++, Java, Basic Linux commands Others: GitHub	
LEADERSHIP EXPERIENCE	
Curriculum Lead, Center of AI in Society (CAIS++)	May 2022-Present
• Lead a group of 5-7 new members through the CAIS++ Machine Learning and Artificial Intelligence curriculum.	
Created Google Collab notebooks to facilitate hands-on learning of AI concepts.	
Recruitment Chair, Theta Tau Kappa Epsilon (USC's professional engineering society)	May 2022-Present
• Organised several social, professional and service recruitment events for 150+ actives and potential new members.	
Professional Chair, Theta Tau Kappa Epsilon (USC's professional engineering society)	Jan 2022-May 2022
• Organised workshops, networking sessions, and industry representative panels for 50+ Theta Tau members.	
WORK EXPERIENCE	
Course Producer, University of Southern California	August 2022-Present
• Lead lab sections for Fundamentals of Computation course (CS 102) to review programming concepts discussed in lecture	
• Explained technical concepts in clear and understandable ways during weekly office hours in order to provide additional sup	port for students.
Embedded Systems Test Engineering Intern, Cruise LLC	May 2022-August 2022
• Developed an analysis tool in Python that helped automate stack launch issue identification and developed metrics and trend	ds on issue count and type.
• Tool enabled frequency and probability analysis of issue occurrence to understand and thereby improve systems	
• Tool projected to decrease debugging and root cause analysis time by 50% and increase developer productivity by enabling	issue prioritisation.
RESEARCH EXPERIENCE	
Undergraduate Researcher at RoboLand, University of Southern California	Aug 2021-May2022
 Building a servo-based robot and synchronising motors and developing gaits. 	
 Implementing gait adaptation for path selection based on robot-obstacle interactions. 	
Undergraduate Researcher at the Evolutionary Adaptive Systems Research Group, Indiana University	Aug 2020-May 2021
• Researched effect of noise in transferring robots from simulation to reality in Evolutionary Robotics.	
• Simulated a simple robot in Python and developed a control system by evolving Continuous-Time Recurrent Neural Network	s using Genetic Algorithms.
• Presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern Undergraduate Cognitive Science Conference and awarded 1st place among 8 other presented research at the Midwestern At	resenters.
Undergraduate team member at the BCI-FNIS research group, Indiana University	Jan 2021-Jun 2021
• Enabled OSC client triggered 'scene' switch functionality by setting up server receiving functions and an OSC client.	
• Wrote python classes to convert raw EEG signals into a format acceptable by an existing Convoluted Neural Network employed	oying Fast Fourier Transform
and Finite Impulse Response filter; included run-time and memory usage checks to compare between classes.	

PROJECTS

Social Queue Detector for members with Autism

- Designed and created a device that processes images and speech to establish cause-effect relationship between words and emotional response as an aid for members with autism
- Used Machine Learning models to detect emotion through facial recognition and convert speech to text on the cloud, and published data to Raspberry Pi using a MQTT protocol

Distracted-Driving preventing Brain-Computer-Interface

- Hacked into a 'MindFlex' electroencephalogram (EEG) toy to acquire brain-electrical activity in addition to interaction data (through a physical button) with an Arduino micro-controller.
- Scripted Python code to store serial input data into CSV files and to train a Multi-Layered Perceptron to detect distracted driving (with PyTorch).
- Designed circuitry and wrote memory optimised Arduino code to read brain activity, implement trained Neural Network, and control buzzer for the final Neuro-feedback device.

Single-Legged Robot

- Designed and constructed a mechanical version of a simulated robot with an Arduino to integrate servos, distance sensors, custom circuit with LEDs and buttons designed on a PCB board, and custom 3D printed parts.
- Developed Computer-Aided Design (Fusion360), Laser Cutting, Soldering, and general Mechatronics skills.

Jan 2021-May 2021

Jan 2022-May 2022

May 2021-Jun 2021